Effective Programming and Data Types in Matlab

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1 Optimizing M-files: Vectorization

In this section, we discuss vectorization – the main technique used in optimizing Matlab code. In general, vectorization entails carrying out computations on data stored as vectors (or matrices) using either linear algebra capabilities of Matlab or Matlab’s built-in functions that operate on vectors. As a general rule, loops are slow and one should instead utilize Matlab’s extensive matrix/vector capabilities whenever possible; the reason is that Matlab’s matrix/vector operations are fully optimized. Moreover, readers can be referred to MathWorks’ website for a more detailed guide for code vectorization. Its web page is on

http://www.mathworks.com/support/tech-notes/1100/1109.html

We have already seen examples of vectorization in our discussion of logical subscripting. For example, the problem in which we wanted to zero out the elements of a given matrix which fell below a given tolerance could have also been programmed using a double for loop, which would also work but would be slower; the use of logical subscripting in that example was an example vectorization. Here we discuss further options to vectorize Matlab code.

Example 1. Our first example of vectorizing a piece of code uses again the idea of logical subscripting. Say we are given two \( n \times n \) matrices \( A \) and \( B \) and we want to form a matrix \( C \) which is defined by \( C_{ij} = \max(A_{ij}, B_{ij}) \); one way to solve this problem is to proceed as follows:

\[
C = \text{zeros}(n);
\]
\[
\text{for } i = 1 : n \\
\quad \text{for } j = 1 : n \\
\quad \quad C(i,j) = \max(A(i,j), B(i,j));
\]
\[
\text{end}
\]
\[
\text{end}
\]

However, the following (vectorized) version is both shorter and more efficient:

\[
C = B;
\]
\[
I = A>B;
\]
\[
C(I)=A(I);
\]

Example 2. Another example that shows exactly the same idea of logic subscripting is as follow. Given a \( 200 \times 400 \) matrix, we want to find out all entries that are smaller than zero, and set them to be zero. You can prepare such matrix \( A \) by typing \( A=\text{rand}(200,400)-0.5; \). The non-vectorized code takes much time to finish the problem:

\[
\text{tic}
\]
\[
[m,n]=\text{size}(A)
\]
\[
\text{for } i=1:m
\]

\[
\text{end}
\]
for j=1:n
    if A(i,j)<0
        A(i,j)=0;
    end
end
toc

This is what C language programming does. The vectorized code does it concisely and efficiently.

tic
A(A<0)=0;
toc

The elapsed time are 0.1600 and 0.0500, respectively (on the same machine). Isn’t it shocking? The above examples show the spirit of vectorization in general; we would like to replace loops by operations that utilize Matlab’s matrix/vector capabilities. The next example is more mathematical in nature.

Example 3. Given two vectors \( \mathbf{a} \) and \( \mathbf{b} \), one defines their tensor product \( \mathbf{a} \otimes \mathbf{b} \) (a matrix) by the following

\[
(a \otimes b)_{ij} = a_i b_j.
\]

The following Matlab function returns the tensor product of the vectors \( \mathbf{a} \) and \( \mathbf{b} \):

function C=tensor1(a,b)
n = length(a);
C = zeros(n);
    for i = 1 : n
        for j = 1 : n
            C(i,j) = a(i)*b(j);
        end
    end

The following vectorized code does the same thing much more efficiently (at the same time a much shorter code too):

function C=tensor2(a,b)
C = a(:)*b(:).'; % column * row

Here, \( a(:) \) converts any row or column vector into a column. \( b(:).' \) is the non-conjugate transpose. For more information, type help transpose, and help ctranspose.

You can test these two codes like below.

\[
\begin{align*}
>> &a=[1:1000]; \\
>> &b=[1000:-1:1]; \\
>> &tic; tensor1(a,b); toc \\
>> &tic; tensor2(a,b); toc
\end{align*}
\]
<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\text{min}</td>
<td>Find the smallest component</td>
</tr>
<tr>
<td>\text{max}</td>
<td>Find the largest component</td>
</tr>
<tr>
<td>\text{sum}</td>
<td>Find the sum of array elements</td>
</tr>
<tr>
<td>\text{cumsum}</td>
<td>Find cumulative sum</td>
</tr>
<tr>
<td>\text{find}</td>
<td>Find indices and values of nonzero elements</td>
</tr>
<tr>
<td>\text{all}</td>
<td>Test to determine if all elements are nonzero</td>
</tr>
<tr>
<td>\text{any}</td>
<td>Test for any non-zeros</td>
</tr>
<tr>
<td>\text{prod}</td>
<td>Find product of array elements</td>
</tr>
<tr>
<td>\text{cumprod}</td>
<td>Find the cumulative product of array elements</td>
</tr>
<tr>
<td>\text{repmat}</td>
<td>Replicate and tile an array</td>
</tr>
<tr>
<td>\text{reshape}</td>
<td>Change the shape of an array</td>
</tr>
<tr>
<td>\text{sort}</td>
<td>Sort array elements in ascending or descending order</td>
</tr>
<tr>
<td>\text{unique}</td>
<td>Find unique elements of a set</td>
</tr>
</tbody>
</table>

Table 1: Some of the Matlab’s built-in functions used in vectorization

The elapsed time are 0.1300 and 0.0300, respectively (on the same machine). More sophisticated vectorization uses Matlab’s built-in function which operate on vectors. Table ?? lists some of the most commonly used Matlab functions in vectorization.

**Example 4.** Consider the operation of computing the scalar product of two \(n \times n\) matrices with real entries. We define,

\[ A \cdot B = \sum_{i=1}^{n} \sum_{j=1}^{n} A_{ij}B_{ij}. \]

The Matlab function \texttt{testmatrixdot} in the next page provides two implementations of the the above operation in the subfunction \texttt{scalar_for} and \texttt{scalar_vec}. The function \texttt{testmatrixdot} receives \(n\) as an input parameter, generates two \(n \times n\) random matrices \(A\) and \(B\) and computes the wall clock run time of both vectorized and non-vectorized version for purposes of comparison.

For example, with \(n = 6000\) the following result was obtained:

Experiment with \(n = 6000\)
For the non-vectorized version \(t = 5.31\)
For the vectorized version \(t = 0.47\)

Note that timing results will vary depending on the machine on which the code is run.

function testmatrixdot(n)
A = rand(n);
B = rand(n);
tic
c = scalar_for(A,B);
t1 = toc;

 tic;
c = scalar_vec(A,B);
t2 = toc;

fprintf('Experiment with n = %i
', n);
fprintf('For the non-vectorized version t = %5.2f
', t1);
fprintf('For the vectorized version t = %5.2f
', t2);

function c = scalar_vec(A,B)
c = sum(A(:).*B(:));

function c = scalar_for(A,B)
c = 0;
[n unused] = size(A);
for i = 1 : n
    for j = 1 : n
        c = c + A(i,j)*B(i,j);
    end
end

The benefit of vectorization can also be illustrated by the example of matrix function of two vectors. In some problems, we have two variables in the form of vectors. Each point in one vector need calculating with the other vector through the function. This gives us a grid, and we need to evaluate at every point on the grid. For non-vectorized code, it results in double loops. However, Matlab can perform it with matrix operations.

Example 5. Consider a saddle function \( f(x, y) \) of two variables

\[
f(x, y) = x^2 - 2y^2,
\]

where \( x \) and \( y \) are vectors. Suppose that \( x \) and \( y \) are in the interval \([-30, 30]\). We can prepare data as below:

\[
x =-30:.3:30;
y = x;
[X,Y] = meshgrid(x,y);
Z = X.^2-2*Y.^2;
mesh(X,Y,Z)
title('saddle')
This shows you how to evaluate the function of two vectors at every points. In the second line \texttt{meshgrid} replicates vector \( x \) and \( y \) into arrays \( X \) and \( Y \), where the rows of the output array \( X \) are copies of the vector \( x \) and the columns of the output array \( Y \) are copies of the vector \( y \). After this, we can get a grid of values of \( Z \) by matrix operations. \texttt{mesh} is a function that produces 3-D mesh surface plots. This example's graph is shown in Figure 1.

![Figure 1: Figure of saddle function](image)

## 2 Composite Data Types

### 2.1 Struct

The Matlab \texttt{struct} data type can store different types of data into a single variable. It is similar to the records in a database, which store a sequence of associated data.

There are two ways to define a \texttt{struct} type of data. First, it can be defined by assigned values directly. For example,

\begin{verbatim}
>>A.a1='abcd';
>>A.a2=100;
>>A.a3=[1 2 3 4];
>>A
A =
    a1: 'abcd'
    a2: 2
\end{verbatim}
2 COMPOSITE DATA TYPES

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
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<tbody>
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<td>struct</td>
<td>Create or convert to structure array</td>
</tr>
<tr>
<td>fieldname</td>
<td>Get structure field names</td>
</tr>
<tr>
<td>getfield</td>
<td>Get structure field contents</td>
</tr>
<tr>
<td>setfield</td>
<td>Set structure field contents</td>
</tr>
<tr>
<td>rmfield</td>
<td>Remove fields from a structure array</td>
</tr>
<tr>
<td>isfield</td>
<td>True if field is in structure array</td>
</tr>
<tr>
<td>isstruct</td>
<td>True if a variable is a structure</td>
</tr>
</tbody>
</table>

Table 2: Some functions for structre type of variables.

a3: [1 2 3 4]

In this example, before the “.” operator in A.a1, A gives the structure’s name. After the “.” operator are three fields a1, a2 and a3. You can access a certain fields by using “.” operation, like A.a2, which gives you 100.

Another way to define a structure is by using function struct. See the same example.

```matlab
>> A = struct ('a1', 'abcd', 'a2', 100, 'a3', [1 2 3 4])
A =
    a1: 'abcd'
    a2: 100
    a3: [1 2 3 4]
```

In the function struct, parameters are field name and field value in alternative. Table ?? lists some functions for structure type of variables.

2.2 Cell Arrays

Cell array is similar to structure in that they collect different types and sizes of data into a single array. You can view a cell arry as a special matrix, where each entry can be of different data types and sizes. You can access individual entry by using the same matrix index as they are in ordinary matrices. For example, we define a 2 × 2 cell array cellA as below. Entries in cellA are of different types and sizes.

```matlab
>> A = [1 2; 3 4];
>> B = 'abcd';
>> C = 1:5;
>> D = ones(3);
>> cellA = {A B; C D}
```

`cellA` =
2.2 Cell Arrays

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>cell</td>
<td>Create cell array</td>
</tr>
<tr>
<td>cellfun</td>
<td>Functions on cell array contents</td>
</tr>
<tr>
<td>celldisp</td>
<td>Display cell array contents</td>
</tr>
<tr>
<td>cellplot</td>
<td>Display graphical depiction of cell array</td>
</tr>
<tr>
<td>num2cell</td>
<td>Convert numeric array into cell array</td>
</tr>
<tr>
<td>cell2struct</td>
<td>Convert cell array to structure array</td>
</tr>
<tr>
<td>struct2cell</td>
<td>Convert structure array to cell array</td>
</tr>
<tr>
<td>iscell</td>
<td>True for cell array</td>
</tr>
</tbody>
</table>

Table 3: Some functions for cell type of variables.

You can access an individual entry by using its index, like

```matlab
>>cellA{1,1}
```

ans =

```
    1  2
    3  4
```

Notice that we use ‘{‘ and ‘}’ to enclose the index to obtain the entry. If we use ‘(’ and ‘)’, Matlab returns the compressed form of this entry.

```matlab
>>cellA(1,1)
```

ans =

```
[2x2 double]
```

Table ?? lists some functions for cell type of variables. For example, we can display the structure of a cell array as nested colored boxes. Type in command window

```matlab
cellplot(cellA)
```

We can see the result in Figure ??
Figure 2: cellplot(cellA).